



8903/PB

Profibus

Communications Option

Technical Manual

HA469267U001 Issue 5

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Safety Information



Requirements

IMPORTANT: Please read this information BEFORE installing the equipment.

Intended Users

This manual is to be made available to all persons who are required to install, configure or service equipment described herein, or any other associated operation.

The information given is intended to highlight safety issues, EMC considerations, and to enable the user to obtain maximum benefit from the equipment.

Complete the following table for future reference detailing how the unit is to be installed and used.

| INSTALLATION DETAILS | |
|--|--|
| Model Number (see product label) | |
| Where installed (for your own information) | |
| Unit used as a: (refer to Certification for the Inverter) | <input type="radio"/> Component <input type="radio"/> Relevant Apparatus |
| Unit fitted: | <input type="radio"/> Wall-mounted <input type="radio"/> Enclosure |

Application Area

The equipment described is intended for industrial motor speed control utilising DC motors, AC induction or AC synchronous machines

Personnel

Installation, operation and maintenance of the equipment should be carried out by qualified personnel. A qualified person is someone who is technically competent and familiar with all safety information and established safety practices; with the installation process, operation and maintenance of this equipment; and with all the hazards involved.

Product Warnings

| | | | | | |
|--|--|--|--|--|--|
| | Caution Risk of electric shock | | Caution Refer to documentation | | Earth/Ground Protective Conductor Terminal |
|--|--|--|--|--|--|

Safety Information



Hazards

DANGER! - Ignoring the following may result in injury

1. This equipment can endanger life by exposure to rotating machinery and high voltages.
2. The equipment must be permanently earthed due to the high earth leakage current, and the drive motor must be connected to an appropriate safety earth.
3. Ensure all incoming supplies are isolated before working on the equipment. Be aware that there may be more than one supply connection to the drive.
4. There may still be dangerous voltages present at power terminals (motor output, supply input phases, DC bus and the brake, where fitted) when the motor is at standstill or is stopped.
5. For measurements use only a meter to IEC 61010 (CAT III or higher). Always begin using the highest range. CAT I and CAT II meters must not be used on this product.
6. Allow at least 5 minutes for the drive's capacitors to discharge to safe voltage levels (<50V). Use the specified meter capable of measuring up to 1000V dc & ac rms to confirm that less than 50V is present between all power terminals and earth.
7. Unless otherwise stated, this product must NOT be dismantled. In the event of a fault the drive must be returned. Refer to "Routine Maintenance and Repair".

WARNING! - Ignoring the following may result in injury or damage to equipment

SAFETY

Where there is conflict between EMC and Safety requirements, personnel safety shall always take precedence.

- Never perform high voltage resistance checks on the wiring without first disconnecting the drive from the circuit being tested.
- Whilst ensuring ventilation is sufficient, provide guarding and /or additional safety systems to prevent injury or damage to equipment.
- When replacing a drive in an application and before returning to use, it is essential that all user defined parameters for the product's operation are correctly installed.

- All control and signal terminals are SELV, i.e. protected by double insulation. Ensure all external wiring is rated for the highest system voltage.
- Thermal sensors contained within the motor must have at least basic insulation.
- All exposed metalwork in the Inverter is protected by basic insulation and bonded to a safety earth.
- RCDs are not recommended for use with this product but, where their use is mandatory, only Type B RCDs should be used.

EMC

- In a domestic environment this product may cause radio interference in which case supplementary mitigation measures may be required.
- This equipment contains electrostatic discharge (ESD) sensitive parts. Observe static control precautions when handling, installing and servicing this product.

- This is a product of the restricted sales distribution class according to IEC 61800-3. It is designated as "professional equipment" as defined in EN61000-3-2. Permission of the supply authority shall be obtained before connection to the low voltage supply.

CAUTION!

APPLICATION RISK

- The specifications, processes and circuitry described herein are for guidance only and may need to be adapted to the user's specific application. We can not guarantee the suitability of the equipment described in this Manual for individual applications.

RISK ASSESSMENT

Under fault conditions, power loss or unintended operating conditions, the drive may not operate as intended. In particular:

- Stored energy might not discharge to safe levels as quickly as suggested, and can still be present even though the drive appears to be switched off
- The motor's direction of rotation might not be controlled
- The motor speed might not be controlled
- The motor might be energised

A drive is a component within a drive system that may influence its operation or effects under a fault condition. Consideration must be given to:

- Stored energy
- Supply disconnects
- Sequencing logic
- Unintended operation

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PROFIBUS COMMUNICATIONS OPTION

Introduction

This manual describes the Parker SSD Drives' Profibus™ Communications Option.

Product Features

- Suitable for use with 890CD Common Bus Drive, 890SD Standalone Drive and 890PX Drive
- LEDs to indicate board and communications status
- Hardware/software selectable Node Address
- Up to 256 DSE input registers and 256 DSE output registers

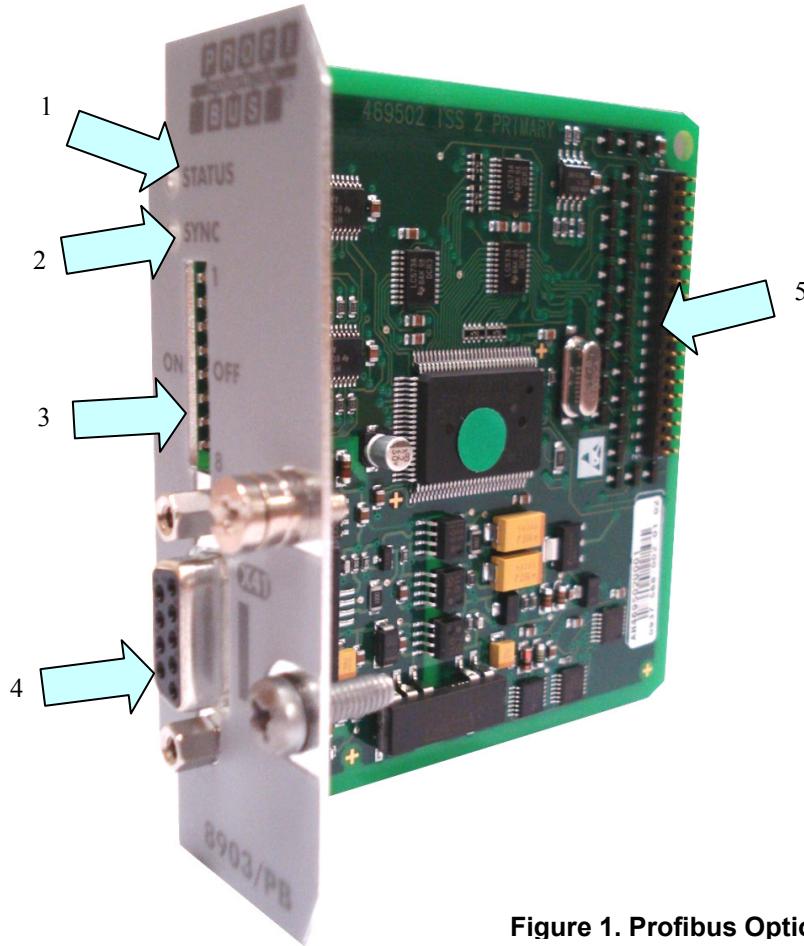


Figure 1. Profibus Option

| | | | |
|---|---------------------------|---|----------------------------------|
| 1 | STATUS LED | 4 | X41 - Profibus Network Connector |
| 2 | SYNC LED - for future use | 5 | Connector to Control Board |
| 3 | Node Address | | |

Product Order Code

Not fitted order code: 8903-PB-00

Factory fitted order code: 890xx-xxxxxxxx-xxx-xxxPx

Compatible Firmware

This option will work with the following versions of 890 firmware:

Version 1.4 onwards

Version 3.1 onwards

Version 2.1 onwards

Version 4.1 onwards

Restrictions

Option must be fitted in Slot A.

Installation

WARNING!

Before installing, ensure that the drive wiring is electrically isolated and cannot be made "live" unintentionally by other personnel. Wait 5 minutes after disconnecting power before working on any part of the system or removing the covers from the drives.

To Remove the Control Board

1. Remove the blanking plates, each secured by a single screw, that fits over the option slots (1).
2. Loosen the top and bottom screws in the handles of the Control Board (2).
3. Pull gently on the handles and slide the Control Board (2) out of the drive.

Note: Save the blanking plate and screw for future use. The drive should not be operated without either an option or a blanking plate fitted. When fitted, these maintain the drive's IP20 rating.

Caution

This Option contains ESD (Electrostatic Discharge) sensitive parts. Observe static control precautions when handling, installing and servicing this Option.



Figure 2. 890 showing Control Board withdrawn with Options fitted

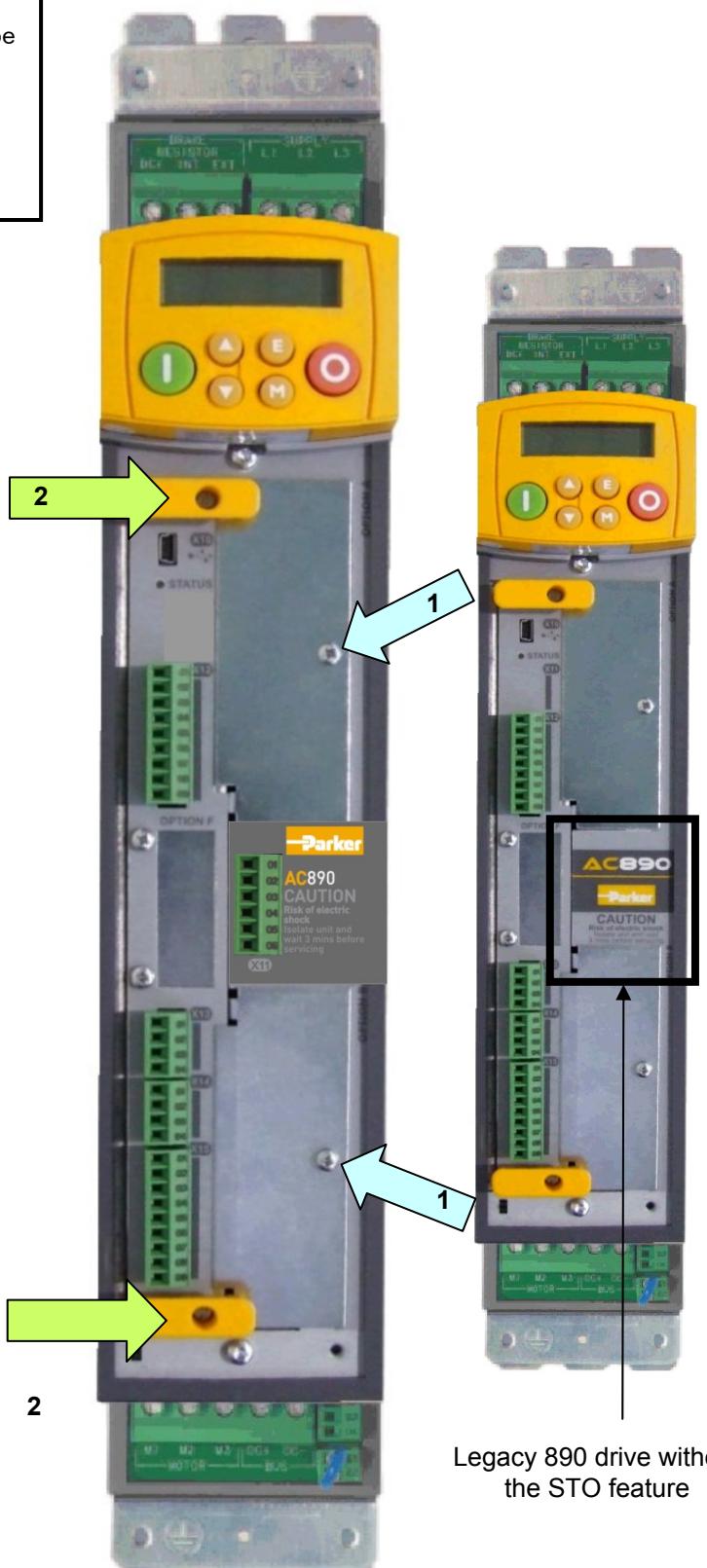


Figure 3. Front of 890 drive showing Control Board fitted

Fitting the Option

The Option fits onto the Control Board.

1. Insert the connector into the Option as shown. The legs of the connector will protrude through into the connector on the other side of the Option.
2. Press the assembly into the **TOP** connector (adjacent to terminals X10, X11 and X12) on the Control Board. Ensure that the front panel of the Option overlaps the front of the Control Board..

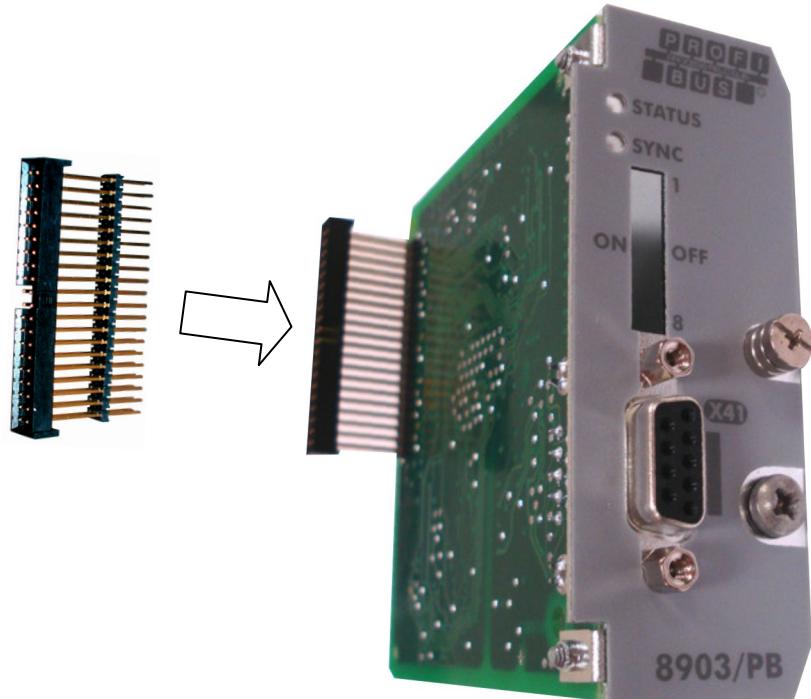


Figure 4. Fitting the connector to the Option

Re-fitting the Control Board

1. Slide the board into the drive, engaging the edges of the boards into the slots. Push until the back edge of the Control Board PCB locates with the connectors in the drive.
2. Tighten in position using the top and bottom screws in the blue handles of the Control Board.
3. Screw the Option in position using the captive screw on the front of the Option.



Figure 5. 890 Control Board with Option fitted

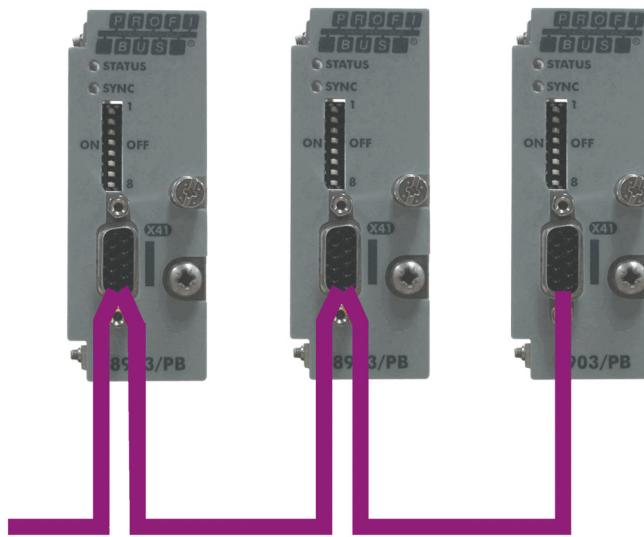
Wiring the System

WARNING!

Before installing, ensure that the drive and all wiring is electrically isolated and cannot be made "live" unintentionally by other personnel.

Wait 5 minutes after disconnecting power before working on any part of the system or removing the covers from the Drive.

Last drive has terminating resistors



Note: It is possible to make serial communications operate without adhering to the following recommendations; however, the recommendations will promote greater reliability.

PROFIBUS-DP Cable Specification

PROFIBUS-DP cable uses a specific colour code (red/green). You should maintain this colour code throughout your network. The cable has a single twisted pair with overall shielding.

The bus line is specified in IEC 61158 and it can be used in accordance with the table below.

| Cable Parameters | PROFIBUS line |
|--|---------------|
| Surge impedance in Ω | 135 ... 165 |
| Capacitance per unit length (pF/m) | < 30 |
| Loop resistance (Ω/km) | 110 |
| Core diameter (mm) | 0.64 |
| Core cross-section (mm^2) | > 0.34 |

Note: Belden B3079E cable meets the above specification.

Maximum Line Length per Bus Segment

Using the specified cable parameters, the maximum line length of a bus segment are as follows:

| | | | | | |
|-------------------------|------|-------|-------|-------|-------|
| Transfer rate in kbit/s | 9.6 | 31.25 | 45.45 | 93.75 | 187.5 |
| Cable length | 1200 | 1200 | 1200 | 1000 | 1000 |
| Transfer rate in kbit/s | 500 | 1500 | 3000 | 6000 | 12000 |
| Cable length | 400 | 200 | 100 | 100 | 100 |

PROFIBUS-DP Connectors

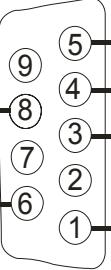
You should use connectors recommended by Profibus. These connectors will have a shield clamp providing shield continuity and will help to ensure good noise immunity of your network.

We recommend the use of the horizontal Erbic range of PROFIBUS-DP connectors from ERNI:

- ◆ ERNI Part number 103648, grey - used on all nodes in the middle of the network
- ◆ ERNI Part number 103649, yellow - termination connector
- ◆ ERNI Part number 134728, grey - includes switchable termination

For further information, visit www.erni.com

Pin Assignment of the Bus Connector

|  | | | |
|---|-------------------|-----------|--|
| Pin Number | PROFIBUS-DP Cable | Signal | Meaning |
| 1 | Braid | Shield | Shield / protective ground |
| 3 | Red (B) | RxD/TxD-P | Receive data / transmission data positive |
| 4 | | CNTR-P | Control signal for repeater (RTS) |
| 5 | | DGND | Data transmission potential (ground to 5V) USE ONLY FOR TERMINATION RESISTORS |
| 6 | | VP | Supply voltage of the terminating resistors-P, (+5V) USE ONLY FOR TERMINATION RESISTORS |
| 8 | Green (A) | RxD/TxD-N | Receive data / transmission data negative |

Earthing the Shield

The PROFIBUS standard suggests that both ends of the transmission line should be connected to safety earth. If you do this, ensure that differences in local earth potential do not allow circulating currents to flow, as not only can these induce large common mode signals in the data lines, but they can also produce potentially dangerous heating in the cable. If in doubt, earth the shield at only one section of the network.

PROFIBUS-DP Network Termination

Failure to terminate a network correctly can reduce the noise immunity of the network and affect performance.

A termination resistor must be fitted at each end of the network to prevent interference.

If too many resistors are fitted to the network, the resulting reduced signal levels may cause nodes to miss bits of information. If network overload becomes excessive, the reduced signal levels may prevent the nodes from detecting any activity.

Connect terminating resistors to the end drives as shown below. (All resistors $\pm 5\%$, minimum $1/4$ Watt).

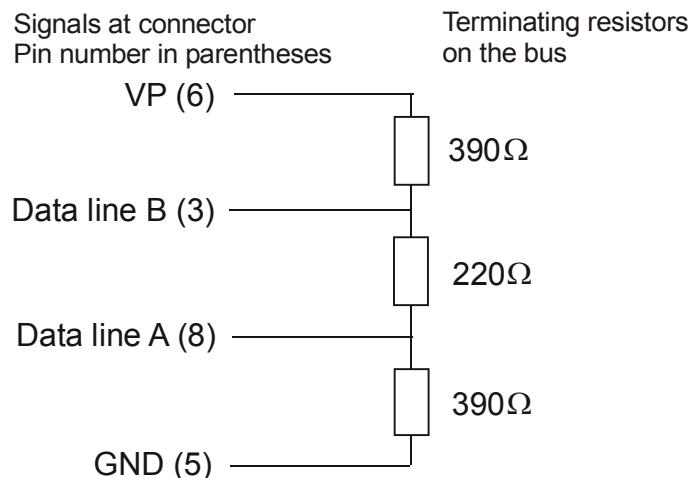


Figure 7. Terminating Resistor Connection

Repeaters

The maximum number of nodes allowed on a single PROFIBUS-DP network segment is 32. A repeater can be used to extend the network length and/or to allow more than 32 nodes to be connected.

Note: *CNTR-P (Pin Number 4) is a TTL level signal that can be connected to a repeater. Most repeaters automatically switch between transmitting and receiving and so do not need this connection.*

Setting Node Address

The DIP switches allow you to select 8 bits for the Node Address (NA) (0-255)

Note: If all 8 bits are in the ON position, the Node Address is set by software.

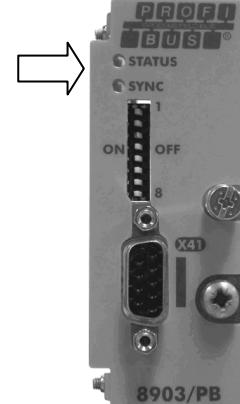
| 8903/PB Front View | DIP Switch | Value | Function | Example | |
|-----------------------|---------------|-------------|-------------------------|---------|---------|
| | 1 | $1 (2^0)$ | Node Address 0 – 255 | 0 OFF | NA = 32 |
| | 2 | $2 (2^1)$ | | 0 OFF | |
| | 3 | $4 (2^2)$ | | 0 OFF | |
| | 4 | $8 (2^3)$ | | 0 OFF | |
| | 5 | $16 (2^4)$ | | 0 OFF | |
| | 6 | $32 (2^5)$ | | 1 ON | |
| | 7 | $64 (2^6)$ | | 0 OFF | |
| | 8 | $128 (2^7)$ | | 0 OFF | |

Note: Only addresses 1 to 125 are valid Profibus addresses.

LED Indications

The STATUS LED indicates the state of the connected network.

The SYNC LED is for future use.



Initial Power-on Checks

With the correct connections to the active PLC/SCADA supervisor, the STATUS LED will light. Refer to Appendix A: Troubleshooting, page 20 for details of LED indications.

Drive Diagnostics

The Profibus MMI View

With the Profibus Option correctly installed, the Keypad will display a set of parameters for PROFIBUS.

These are read-only parameters - diagnostics.

Parameter Descriptions

BAUDRATE *Read Only* *Range: Enumerated - see below*

Baudrate of the Profibus network connection set by PLC.

Enumerated Value : BAUDRATE

- 0 : 12 Mbits/sec
- 1 : 6 Mbits/sec
- 2 : 3 Mbits/sec
- 3 : 1.5 Mbits/sec
- 4 : 500 kbits/sec
- 5 : 187.5 kbits/sec
- 6 : 93.75 kbits/sec
- 7 : 45.45 kbits/sec
- 8 : 19.25 kbits/sec
- 9 : 9.6 kbits/sec
- 10 : UNKNOWN - auto baud not completed

ADDRESS *Read Only* *Range: 0 to 125*

The Profibus node address.

If all the DIP switches are set to ON, the Address is set by the DSE configuration.

A specific Address can be set using the DIP switches. Refer to "Setting Node Address", page 8.

If all the DIP switches are set to OFF (i.e. the Address is set to zero) the Profibus option is disabled and does not appear on the Profibus network (see the STATUS parameter below).

STATUS *Read Only* *Range: Enumerated - see below*

State of the ControlNet network connection.

Enumerated Value : STATUS

- 0 : MISSING OR FAULT
- 1 : DISABLED
- 2 : BAUD SEARCH
- 3 : WAIT PARAM
- 4 : WAIT CONFIG
- 5 : DATA EXCHANGE
- 6 : DATA EXCH NO WD
- 7 : DATA EXCH ERROR
- 8 : DATA EXCH ER NO WD

ADDRESS METHOD *Read Only* *Range: Enumerated - see below*

Diagnostic showing the node address setting method. If all of the Address switches on the Profibus Option are set ON, then the method is HARDWARE (switches), otherwise it is SOFTWARE (DSE).

Enumerated Value : ADDRESS METHOD

- 0 : SOFTWARE
- 1 : HARDWARE

Configuring the Profibus System

To configure the Profibus system, complete the steps below. Our example is shown using a PLC configured using Siemens STEP7. For other systems, refer to the manufacturer's instructions.

Step 1: Configuring the Profibus Option using DSE

You can configure your Profibus Option using DSE.

Follow the instructions below.

Step 1.1: Inserting a PROFIBUS Function Block

Display your configuration page. Click on the Block menu at the top of the screen.

1. Move the cursor down to select "890 Comms" and select "Profibus".
2. Click to select the Profibus block. Move this to where you want on the screen then click again to place the block.

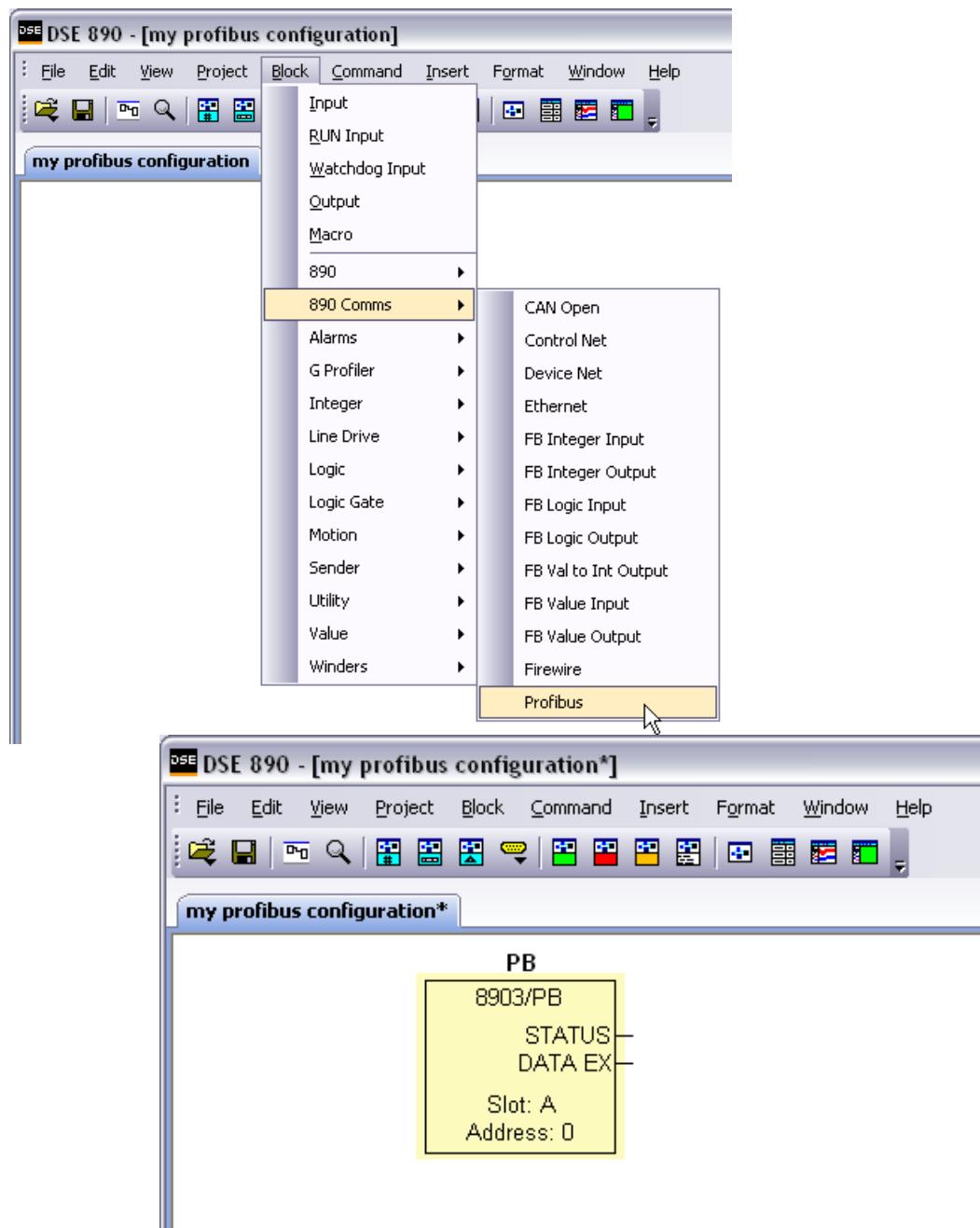


Figure 8. Configuration showing PB function block

Step 1.2: Attaching Fieldbus Connectors

Seven fieldbus connector types are available:

| | | |
|-------------------|-----------------|----------------------|
| FB Integer Input | FB Logic Input | FB Value Input |
| FB Integer Output | FB Logic Output | FB Value Output |
| | | FB Val to Int Output |

Input connector: the data is sent from PLC → 890

Output connector: the data is sent from 890 → PLC

The fieldbus connectors must be added before they will appear in the Profibus function block.

Note: *The function block and connectors can be renamed by using the right mouse button and selecting **Rename Block**.*

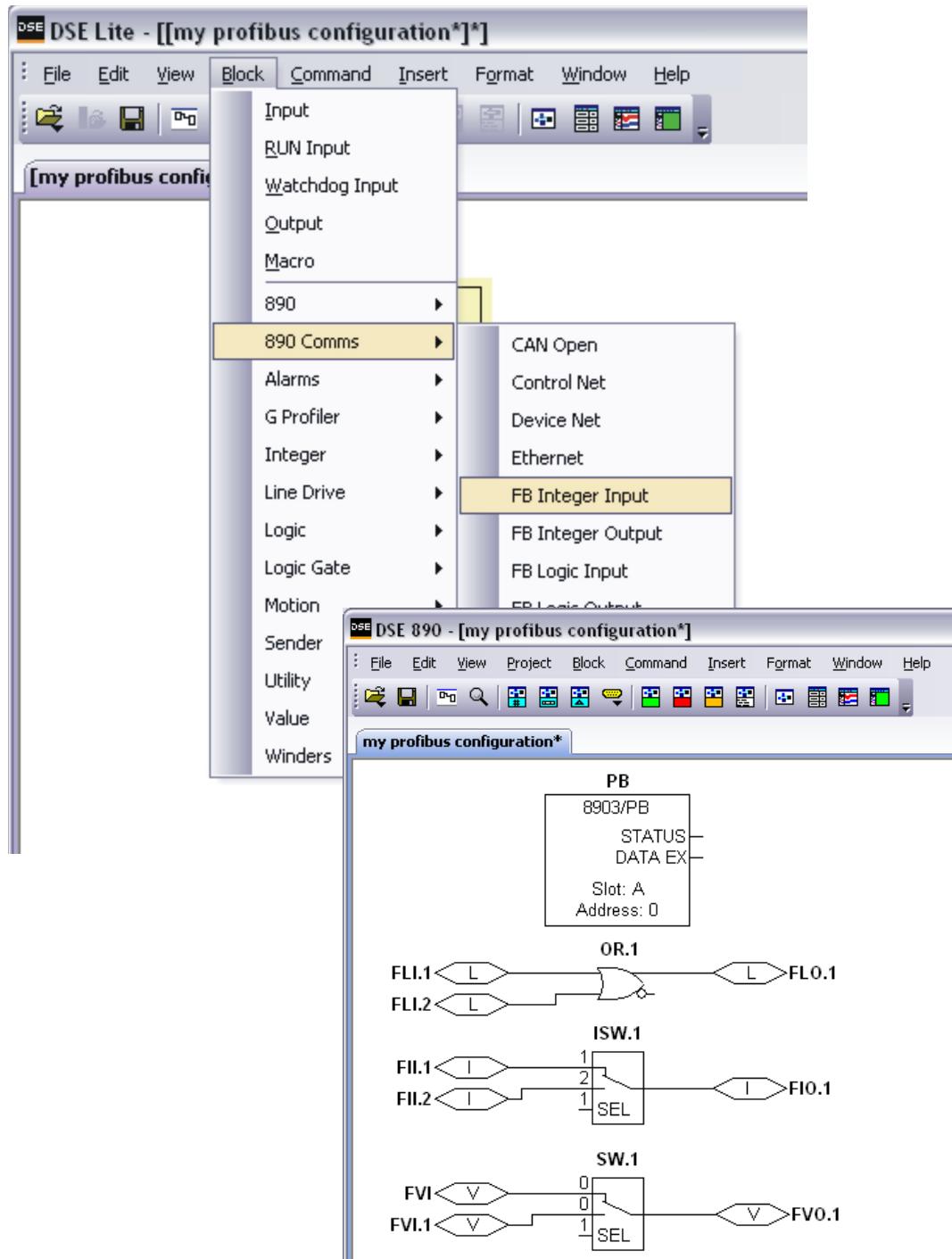
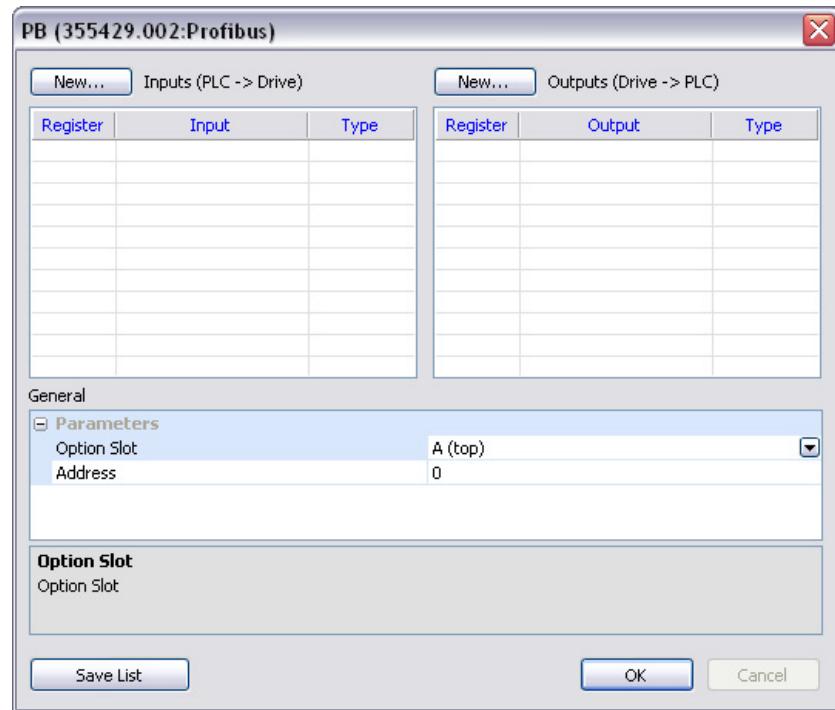


Figure 9. Configuration showing PB function block and Fieldbus Connectors

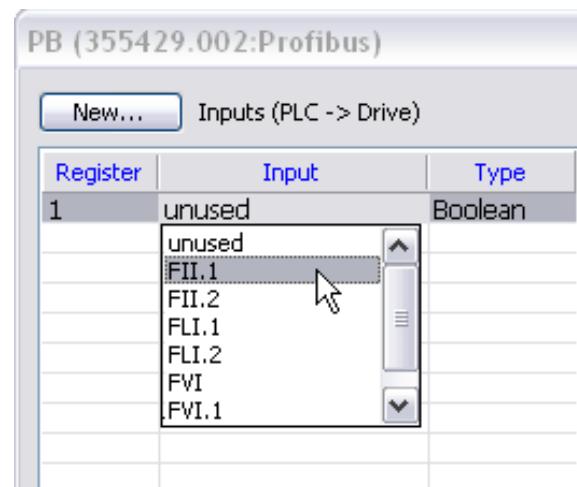
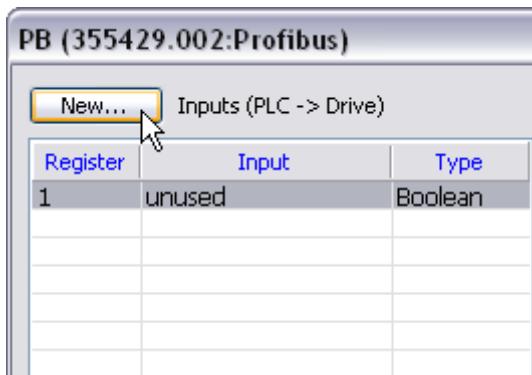
Step 1.3: Configuring the Fieldbus Connectors

Double-click on the function block to display the dialog below. The fieldbus connectors (inputs and outputs) are assignable in the function block along with their data type to/from the PLC. The option slot and Address can also be selected.

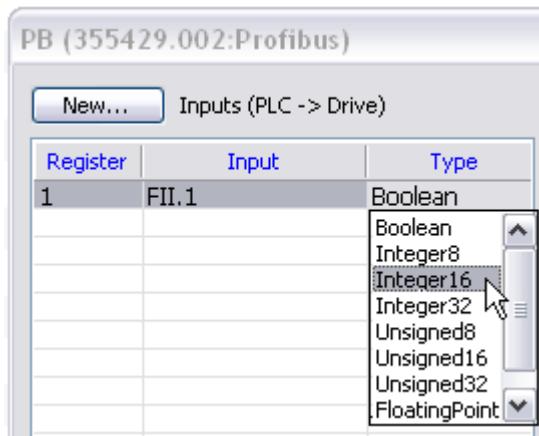


To configure the input and output connectors you have placed in the configuration:

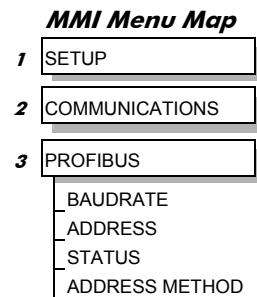
1. Click on **New...** to add Inputs or Outputs to table.
2. Select the drop-down menu below **Input** to choose the required input connector to be mapped to the Register. For example below, Register 1 "Input" is shown with the possible fieldbus selections that have been placed in the configuration: FII.1 (Fieldbus Integer Input 1), FLI.1 (Fieldbus Logic Input 1), FVI.1 (Fieldbus Value Input 1) etc.



3. Select the drop down menu below **Type** to choose the required PLC type on Register 1, for example.



4. Set up all the input/output registers in a similar way.
 5. The Address can be selected in the range 0 – 125. This can be confirmed by the ADDRESS diagnostic on the Keypad.



Note: The Address set in DSE will only be used if the Address switches on the Profibus Option are set to ON.
 If the Address is set to zero and the switches on the Profibus Option are all set to ON, the option is disabled and will not appear on the Profibus network.

6. "Option Slot" = A (top). The Profibus Option can only be fitted in the OPTION A slot on the front of the drive. This is the default setting for "Option Slot".

DSE Data Types

| Data Type | Description | Range |
|-----------|--------------------------|---------------------------------|
| LOGIC | Logic | False (F) and True (T) |
| INTEGER | 32-bit signed integer | -2,147,483,648 to 2,147,483,647 |
| VALUE | 32-bit fixed point value | -32768.0 to 32767.9999 |

Profibus PLC Data Types

| Data Type | Description | Range | PLC Size |
|---------------|--------------------------------------|---------------------------------|----------|
| Boolean | 8-bit Boolean | False (0x00) and True (0x01) | byte |
| Integer8 | 8-bit signed integer | -128 to 127 | byte |
| Integer16 | 16-bit signed integer | -32,768 to 32,767 | word |
| Integer32 | 32-bit signed integer | -2,147,438,648 to 2,147,483,647 | dword |
| Unsigned8 | 8-bit unsigned integer | 0 to 255 | byte |
| Unsigned16 | 16-bit unsigned integer | 0 to 65,535 | word |
| Unsigned32 | 32-bit unsigned integer | 0 to 4,294,967,295 | dword |
| FloatingPoint | 32-bit IEEE-754 floating-point value | 1.19209290e-38 to 3.4028235e+38 | dword |

Conversion of DSE Type < > Profibus Type

The DSE fieldbus connectors are each assigned a Profibus PLC "Type" as described in "Step 1.3: Configuring the Fieldbus Connectors" on page 12.

The conversion between the DSE type and the PLC type is performed automatically (refer to Appendix B: DSE/Profibus Conversion Rules, page 21).

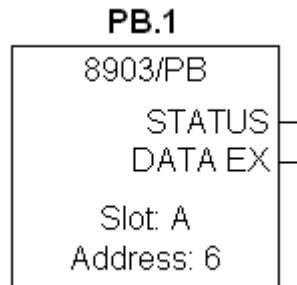
Any PLC type can be assigned to a fieldbus connector

Some recommended PLC type assignments to fieldbus connectors are given in the table below:

| Fieldbus Connector | PLC Type | PLC Size |
|--------------------|---------------|----------|
| LOGIC | Boolean | byte |
| INTEGER | Integer32 | dword |
| VALUE | FloatingPoint | dword |

Profibus Status Information

The Profibus function block in DSE provides status information about the Profibus network interface.



When online, the *actual* Address in use can be found by clicking the right mouse button over the "Address:" text and selecting **Get**. This may be different to the Address set in the function block configuration if the switches on the Option have set the Address.

The function block also provides two status outputs that can be wired to: STATUS and DATA EX.

For example, the DATA EX output could be ANDed with the motor START causing the drive to stop if the PLC connection is lost.

STATUS

Enumerated value:

- Status
- 0: MISSING OR FAULT
- 1: DISABLED
- 2: BAUD SEARCH
- 3: WAIT PARAM
- 4: WAIT CONFIG
- 5: DATA EXCHANGE
- 6: DATA EXCH NO WD
- 7: DATA EXCH ERROR
- 8: DATA EXCH ER NO WD

DATA EX

Logic value:

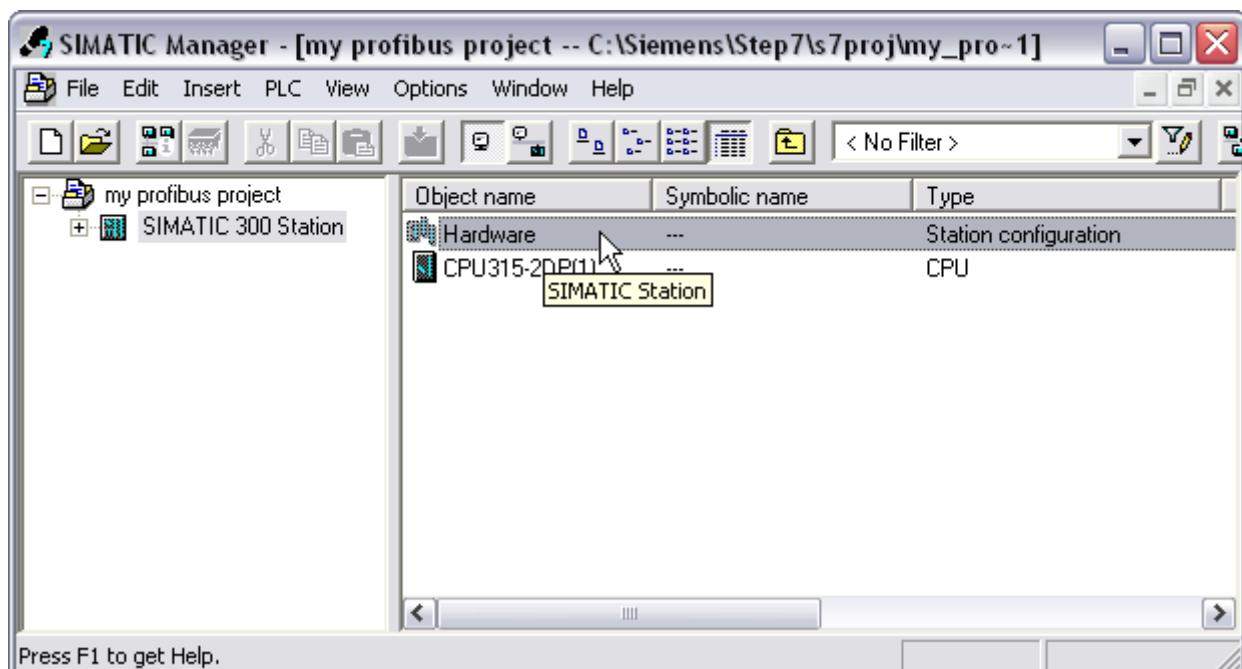
True (T) indicates that the Profibus interface is in the Data Exchange state.

The STATUS output could be used with the LOGIC::LOOKUP function block to determine a particular state.

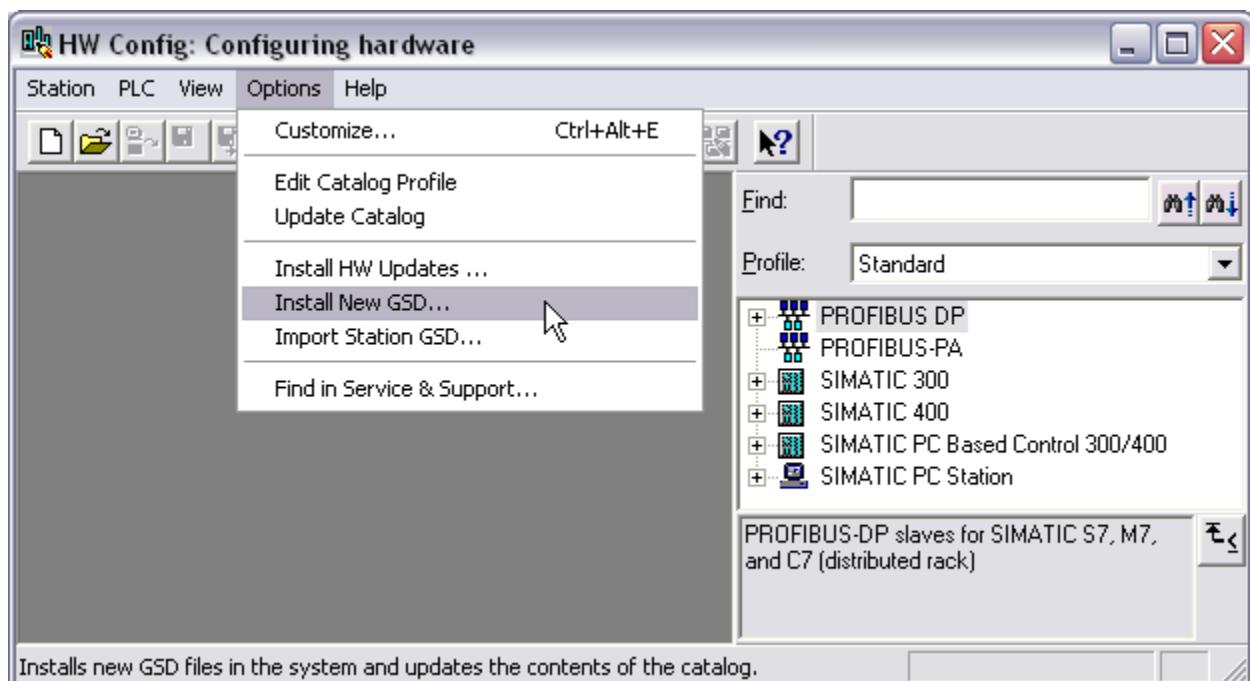
Step 2: Configuring the PLC/SCADA Supervisor

Note: This example uses the Siemens Simatic 7 PROFIBUS configuration tool, Siemens STEP 7 Simatic manager.

1. Create a project selecting the PLC hardware to be used. Click on Hardware...

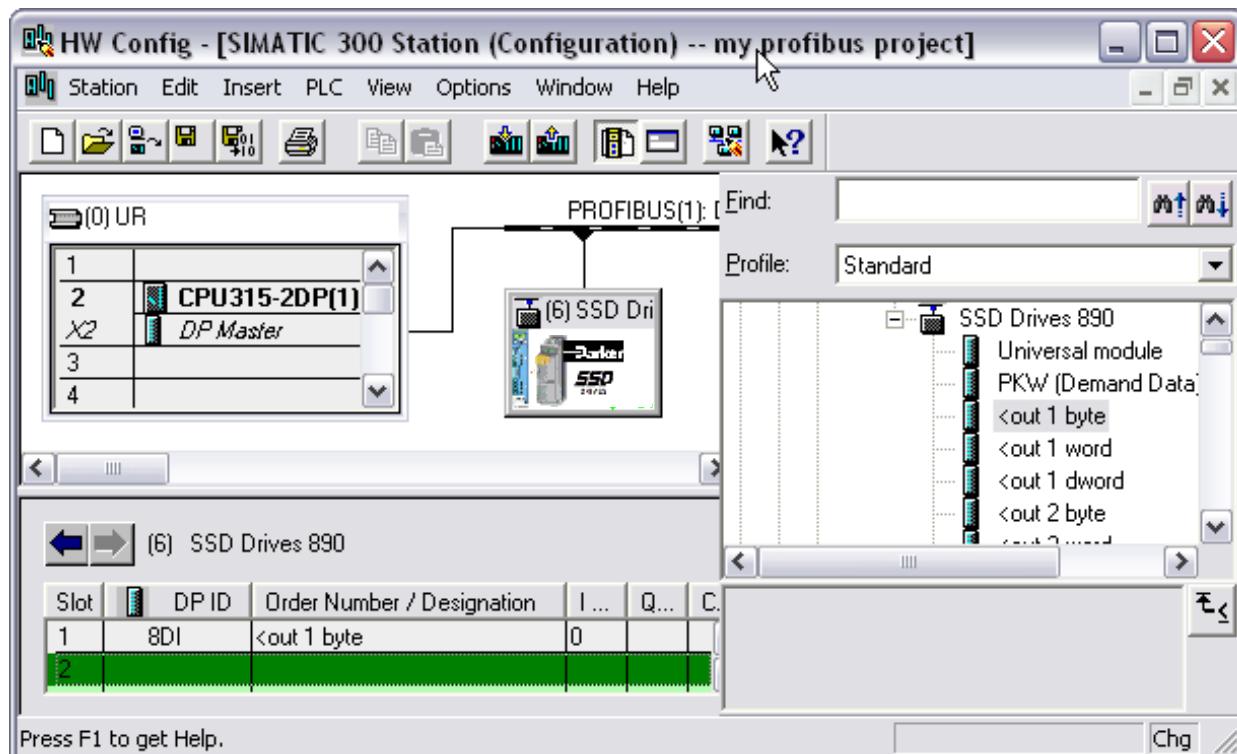


2. Import the GSD file for the 890 so that it appears in the Hardware Catalog. Click on Options...Install New GSD..., then use the file explorer to select the file **ssd4890.gsd**

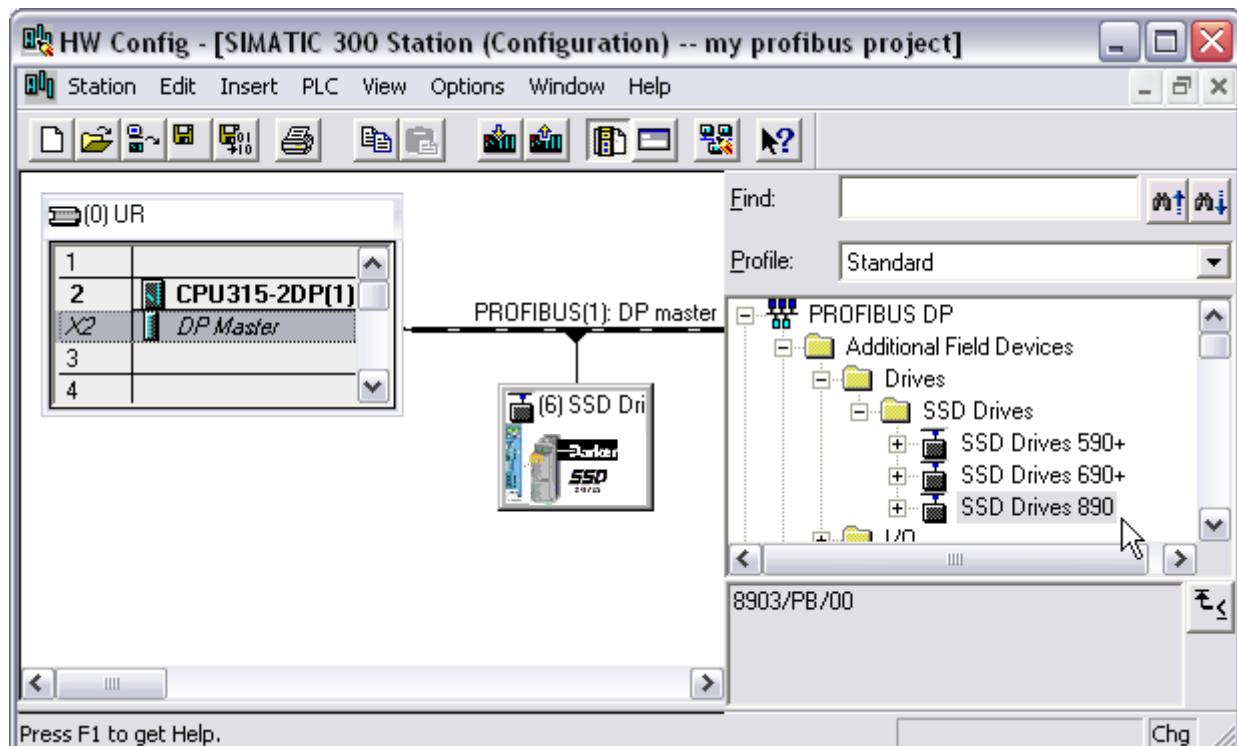


3. Open the project for the Profibus Master. Find the Device Description for the **SSD Drives 890** which can be found under **PROFIBUS DP:Additional Field Devices: Drives:SSD Drives** in the Hardware Catalog window. Select with the mouse and drag

across to the DP Master in the station window.. The required node address for the 890 must be entered when prompted.



4. Configure which 890 registers are to be exchanged with the Master. These are picked from the 890 in the Hardware Catalog window. First click on the 890 icon in the Station window to open the register list for this node in the lower Station window. Select the required module in the Hardware Catalog window and then click or drag to the lower Station window.



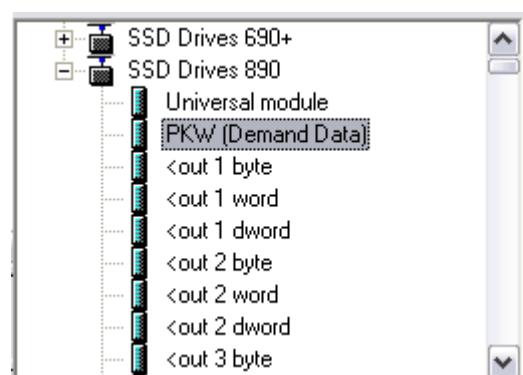
Three types of module can be selected:

1 : PKW (Demand data)

This is to enable cyclic data transfer via the PKW mechanism as defined by PROFIDRIVE V0.

Refer to page 18.

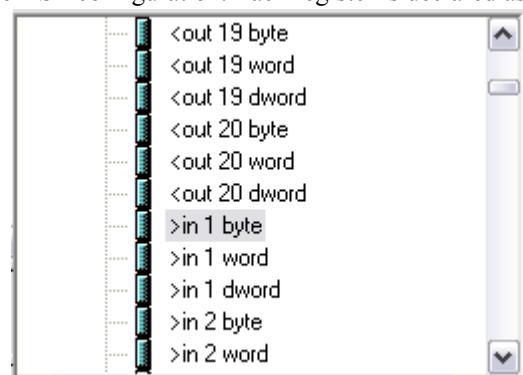
Note: If this feature is required, it must be the first module declared.



2 : User defined Input and Output Registers

These are the registers as declared in the DSE configuration. Each register is declared as being either byte (Boolean, Integer8, Unsigned8), word (Integer16, Unsigned16) or dword (Integer32, Unsigned32, FloatingPoint). The matching module must be selected.

For example, if Input Register 1 (PLC -> Drive) is declared as a Boolean in DSE, then the “>in 1 byte” module must be selected.

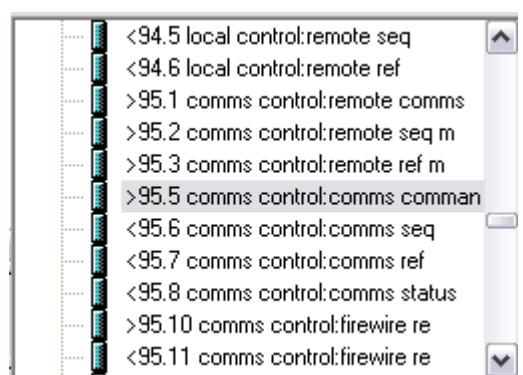


3 : Fixed Parameters

These are Drive parameters that are always present in the 890. They can be found in the Motor Control macro block in DSE Configuration Tool.

For example, selecting the “>95.5 comms control:comms command” module adds the COMMS COMMAND parameter, which has reference 95.5, to the Output Data from the PLC.

Note: For fixed parameters, no configuration is required in the 890. Each parameter has a fixed size / encoding as described in the DSE Configuration Tool.



A combination of the above module types may be included, for example:

| Slot | DP ID | Order Number / Designation | I ... | Q ... | Comment |
|------|-------|-------------------------------|--------|--------|---------|
| 1 | 115 | PKW (Demand Data) | 256... | 256... | |
| 2 | 8D0 | >in 1 byte | | 0 | |
| 3 | 225 | >in 2 dword | | 264... | |
| 4 | 1A0 | >95.5 comms control:comms cor | | 268... | |
| 5 | 1AI | <out 1 word | 264... | | |
| 6 | 1AI | <95.8 comms control:comms sta | 266... | | |
| 7 | | | | | |
| 8 | | | | | |

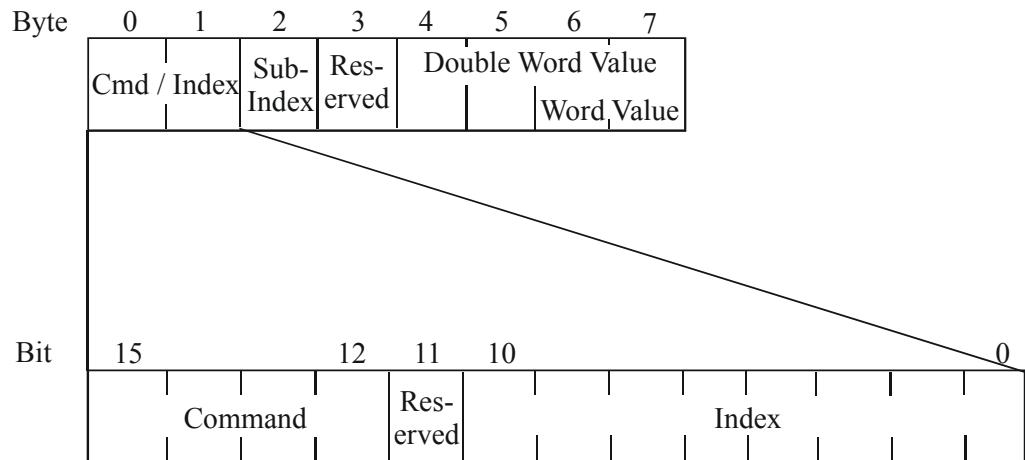
The Network Interface

PKW (Demand Data) Processing

PKW is a sub-protocol using the first 8 bytes (octets) in both the request and response message of the cyclic Data Exchange. It allows random read/write access to any parameter within the Drive. It is enabled by the Profibus-DP- Master setting the first byte of the Cfg_Data to 0x73. A PKW module is contained in the GSD file installed when configuring the PLC/SCADA Supervisor.

The sub-protocol consists of 3 parts:

- **Command**
- **Parameter Reference**
- **Parameter Value or Error Code**



Command

The Command field in the request message selects the required operation. This is either None, Read, Write Word, or Write Double Word.

The Command field in the response message either confirms that no operation has been requested, indicates that a Read or Write request has been completed successfully or indicates that a Read or Write request has failed.

Valid values for the Command field are:

| Command | Request (Master to Slave) | Positive Response (Slave to Master) |
|---------|----------------------------|-------------------------------------|
| 0 | No Command | 0 |
| 1 | Read Request | 1 or 2 |
| 2 | Write Word Request | 1 |
| 3 | Write Double Word Request | 2 |
| 6 | Read Request (array) | 4 or 5 |
| 7 | Write Word Request (array) | 4 |
| 8 | Write Double Word Request | 5 |

The valid Response Codes are:

| Response | Meaning |
|----------|----------------------------------|
| 0 | No Response |
| 1 | Transfer Word |
| 2 | Transfer Double Word |
| 4 | Transfer Word (array) |
| 5 | Transfer Double Word (array) |
| 7 | Request Rejected with error code |

Parameter Reference

The Parameter Reference consists of an Index and a Sub-Index:

- ◆ For User Defined Input Registers, the Index is 254 and the Sub-Index is the Input Register Number
- ◆ For User Defined Output Registers, the Index is 255 and the Sub-Index is the Output Register Number
- ◆ For Fixed Parameters, the Index is the "Block" number and the Sub-Index is the "Parameter" number. These are listed in the GSD file, in the DSE Configuration Tool, or can be displayed on the MMI by holding the "M" key for a few seconds whilst displaying the parameter (PREF).

Parameter Value or Error Code

The Value/Error Code field is used to receive a Read value, send a Write value or receive an error code.

The Value is either a Word (16-bit) or a Double Word (32-bit):

- ◆ If a Word, the value is transferred in octets 6 and 7 of the request and/or response
- ◆ If a Double Word, the value is transferred in octets 4, 5, 6 and 7.

If the Response Command is 7, i.e. the request has been rejected, this field contains the error code. These are:

| Error Code | Meaning |
|------------|--|
| 0 | Invalid Tag Number |
| 1 | Read Only Parameter |
| 2 | Value Under/Over-Range |
| 3 | Incorrect Data Type |
| 17 | Request cannot be processed because of operating state |
| 18 | Other error |

Appendix A: Troubleshooting

890 Profibus Option Status LED

Table 1

| Colour | LED Indication | Description |
|--------|----------------------|--|
| | OFF | Drive is not powered or fault |
| | ON | Drive is not initialised or fault |
| | 75% RED | Disabled. The Node Address has been set to zero. |
| | 50% RED | Baud Search. PLC not connected or halted. |
| | 25% RED | Waiting Parameterisation or waiting Configuration. Either the 890 is not being addressed by the PLC or the 890 is rejecting the Parameterisation or Configuration. |
| | 75% GREEN | Data Exchange with watchdog (response monitoring) enabled. No errors. |
| | 50% GREEN | Data Exchange with watchdog (response monitoring) disabled. |
| | 25% RED 75% GREEN | Data Exchange with watchdog (response monitoring) enabled. Errors detected, e.g. values from PLC out-of-range. |
| | 50% RED 50% GREEN | Data Exchange with watchdog (response monitoring) disabled. Errors detected, e.g. values from PLC out-of-range. |

Table 2

| NETWORK STATES | | |
|----------------|------------------|---|
| 0 | MISSING OR FAULT | No power, not fitted or fault |
| 1 | DISABLED | Option disabled. Address set to 0 |
| 2 | BAUD SEARCH | Baud search. Waiting for communications on Profibus. To allow auto baud. |
| 3 | WAIT PARAM | Waiting for valid parameterisation message to be sent to this node. |
| 4 | WAIT CONFIG | Waiting for valid parameterisation message to be sent to this node. |
| 5 | DATA EXCHANGE | Data Exchanging with watchdog (response monitoring) enabled |
| 6 | DATA EXCH NO WD | Data Exchanging with watchdog (response monitoring) disabled |
| 7 | DATA EXCH ERROR | Data Exchanging with watchdog (response monitoring) enabled with errors. |
| 8 | DATA EX ER NO WD | Data Exchanging with watchdog (response monitoring) disabled with errors. |

Appendix B: DSE/Profibus Conversion Rules

The rules governing the conversion between 890 data types and Profibus PLC data types are given below. Note carefully that some conversions will result in rounding, limiting and truncation of the original value.

LOGIC Type Connector

| | Data from PLC | Data to 890 |
|-------------------------------------|------------------|---------------|
| From BOOLEAN to LOGIC | False True | False True |
| From FLOATING POINT to LOGIC | Zero Non-zero | False True |
| From INTEGER 8 to LOGIC | Zero Non-zero | False True |
| From INTEGER 16 to LOGIC | Zero Non-zero | False True |
| From INTEGER 32 to LOGIC | Zero Non-zero | False True |
| From UNSIGNED 8 to LOGIC | Zero Non-zero | False True |
| From UNSIGNED 16 to LOGIC | Zero Non-zero | False True |
| From UNSIGNED 32 to LOGIC | Zero Non-zero | False True |

| | Data from 890 | Data to PLC |
|-------------------------------------|---------------|---------------|
| From LOGIC to BOOLEAN | False True | False True |
| From LOGIC to FLOATING POINT | False True | 0.0 1.0 |
| From LOGIC to INTEGER 8 | False True | 0 1 |
| From LOGIC to INTEGER 16 | False True | 0 1 |
| From LOGIC to INTEGER 32 | False True | 0 1 |
| From LOGIC to UNSIGNED 8 | False True | 0 1 |
| From LOGIC to UNSIGNED 16 | False True | 0 1 |
| From LOGIC to UNSIGNED 32 | False True | 0 1 |

INTEGER Type Connector

| | Data from PLC | Data to 890 |
|---------------------------------------|---------------------------------|--|
| From BOOLEAN to INTEGER | False True | 0x0000 0000 0x0000 0001 |
| From INTEGER 8 to INTEGER | -128 to 127 | -128 to 127 |
| From INTEGER 16 to INTEGER | -32,768 to 32,767 | -32,768 to 32,767 |
| From INTEGER 32 to INTEGER | -2,147,483,648 to 2,147,483,547 | -2,147,483,648 to 2,147,483,547 |
| From UNSIGNED 8 to INTEGER | 0 to 255 | 0 to 255 |
| From UNSIGNED 16 to INTEGER | 0 to 65,535 | 0 to 65,535 |
| From UNSIGNED 32 to INTEGER | 0 to 4,294,967,295 | 0 to 2,147,483,647 limits apply |
| From FLOATING POINT to INTEGER | 32-bit IEEE floating-point | -2,147,483,648 to 2,147,483,547 Fractional part rounded |

| | Data from 890 | Data to PLC |
|---------------------------------------|---------------------------------|------------------------------------|
| From INTEGER to BOOLEAN | Zero Non-zero | True False |
| From INTEGER to FLOATING POINT | -2,147,483,648 to 2,147,483,647 | 32-bit IEEE floating-point |
| From INTEGER to INTEGER 8 | -2,147,483,648 to 2,147,483,647 | -128 to 127 limits apply |
| From INTEGER to INTEGER 16 | -2,147,483,648 to 2,147,483,647 | -32768 to 32767 limits apply |
| From INTEGER to INTEGER 32 | -2,147,483,648 to 2,147,483,647 | -2,147,483,648 to 2,147,483,647 |
| From INTEGER to UNSIGNED 8 | -2,147,483,648 to 2,147,483,647 | 0 to 255 limits apply |
| From INTEGER to UNSIGNED 16 | -2,147,483,648 to 2,147,483,647 | 0 to 65,535 limits apply |
| From INTEGER to UNSIGNED 32 | -2,147,483,648 to 2,147,483,647 | 0 to 2,147,483,647 limits apply |

VALUE Type Connector

| | Data from PLC | Data to 890 |
|-------------------------------------|---------------------------------|------------------------------------|
| From BOOLEAN to VALUE | False True | 0.0 1.0 |
| From FLOATING POINT to VALUE | 32-bit IEEE floating-point | -32,768.0 to 32,767.9999 |
| From INTEGER 8 to VALUE | -128 to 127 | -128.0 to 127.0 |
| From INTEGER 16 to VALUE | -32,768 to 32,767 | -32,768.0 to 32,767.0 |
| From INTEGER 32 to VALUE | -2,147,483,648 to 2,147,483,547 | -32,768.0 to 32,767.0 limits apply |
| From UNSIGNED 8 to VALUE | 0 to 255 | 0.0 to 255.0 |
| From UNSIGNED 16 to VALUE | 0 to 65,535 | 0.0 to 32,767.0 limits apply |
| From UNSIGNED 32 to VALUE | 0 to 4,294,967,295 | 0.0 to 32,767.0 limits apply |

| | Data from 890 | Data to PLC |
|-------------------------------------|--------------------------|--|
| From VALUE to BOOLEAN | Zero Non-zero | False True |
| From VALUE to FLOATING POINT | -32,768.0 to 32,767.9999 | 32-bit IEEE floating-point |
| From VALUE to INTEGER 8 | -32,768.0 to 32,767.9999 | -128 to 127 limits apply/ rounding applies |
| From VALUE to INTEGER 16 | -32,768.0 to 32,767.9999 | -32,768 to 32,767 limits apply/ rounding applies |
| From VALUE to INTEGER 32 | -32,768.0 to 32,767.9999 | -32768 to 32,767 limits apply/ rounding applies |
| From VALUE to UNSIGNED 8 | -32,768.0 to 32,767.9999 | 0 to 255 limits apply/ rounding applies |
| From VALUE to UNSIGNED 16 | -32,768.0 to 32,767.9999 | 0 to 32767 limits apply/ rounding applies |
| From VALUE to UNSIGNED 32 | -32,768.0 to 32,767.9999 | 0 to 32767 limits apply/ rounding applies |

| ISS. | MODIFICATION | ECN No. | DATE | DRAWN | CHK'D |
|---|---|---|-----------|-------|--------|
| 1 | Initial Issue (HA469267U001) | 17320 | 03/06/05 | CM | KJ |
| 2 | Various small amendments | 19213 | 15/02/06 | CM | KJ |
| 3 | Company name change. | 19591 | 26/04/07 | CM | KJ |
| 4 | New Warranty details New Safety Information | 20358 (20280) | 06/01/09 | CM | KJ |
| 5 | DSE screen shots brought up-to-date Page 11 Replaced six with seven and added FB Val to Int Output. Replaced techcard with Option and Replaced DSE 890 with DSE. Other minor corrections and amendments. | 20814 | 12 Feb 09 | FEP | MF |
| FIRST USED ON | | MODIFICATION RECORD | | | |
| | | 8903/PB Profibus Communications Interface | | | |
|  | | DRAWING NUMBER | | | SHT. 1 |
| | | ZZ469267C001 | | | OF 1 |

